#### Human Exoskeleton

#### Team J

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#### **Project Description**

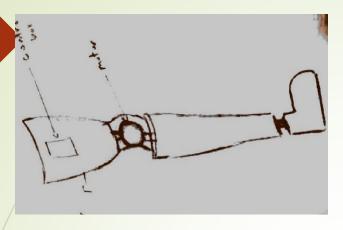
The project is about designing an Adjustable Human-Exoskeleton Mounting Interface.



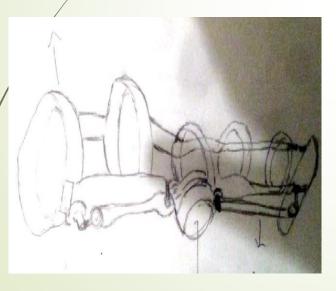
#### **Project Description**

- The team seeks to look into and improve on the following factors:
  - Use strong materials
  - Make the design adjustable
  - Use soft fabric to minimize irritation
  - Ensure that the design is of limited weight
  - Make the system's size reasonable for effectiveness in use and portability

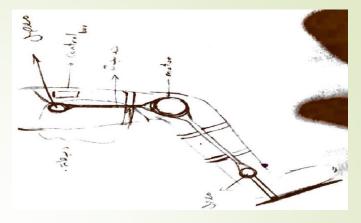
### Design Considered



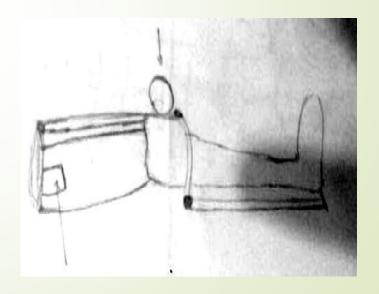
- Adorable to Children
- Hard to wear



- tight to legs.
- Need help to wear



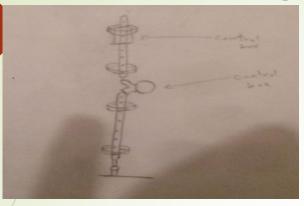
- Flexible
- Take time to wear



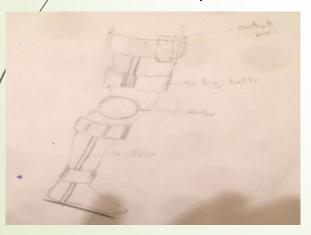
- Controllable
- High weight

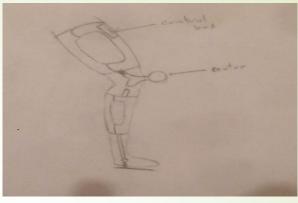
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#### **Designs Considered**

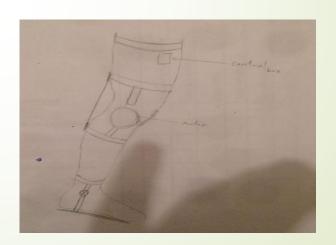


- Lightweight, easy to wear
- Motor takes place





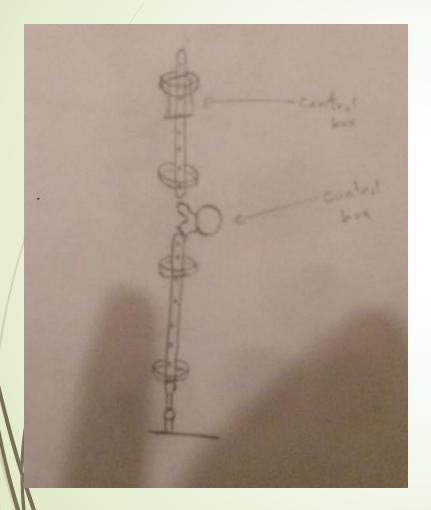
- Adjustable
- Complex to wear

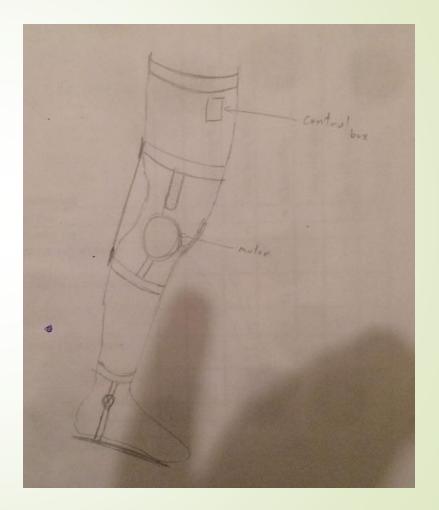


- Low Profile, Lightweight, Insert into normal shoes.
- Hard and expensive to build.

## **Design Selected**

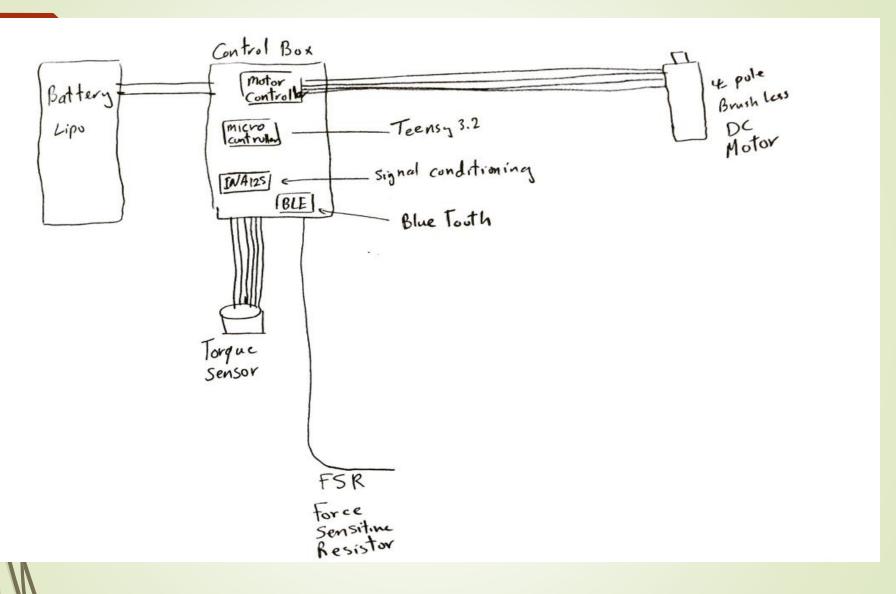




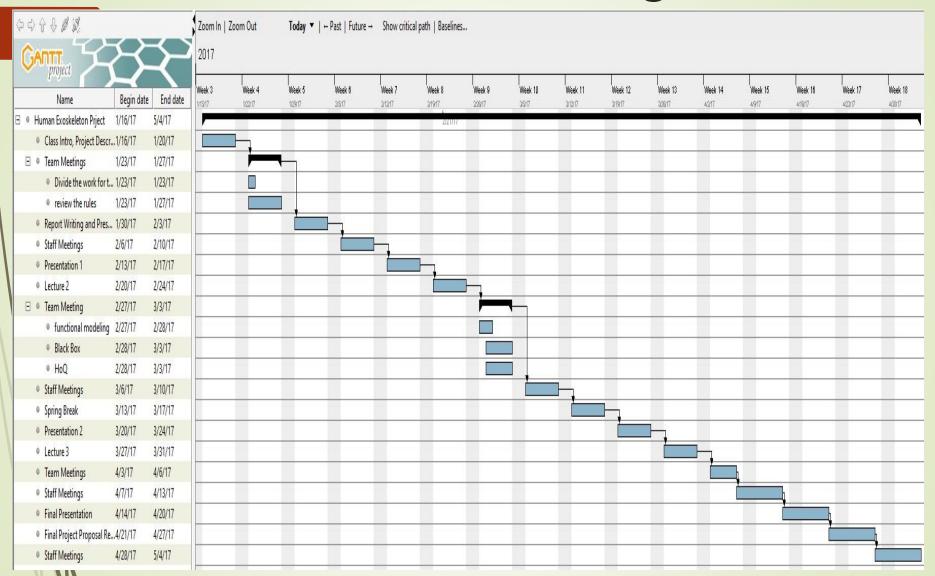


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### Design Selected



### Schedule & Budget



# Budget (\$500+Electric System):-

- Estimated Cost:
- 1- Materials (40%)
- 2- Advertisment (20%)
- 3- Manufacturing (30%)
- 4- Prototyping (10%)

- Electric System:
- 1- FSR (\$20.95)
- 2- Micro-controller (\$22.80)
- 3- Blue-tooth (\$24.95)
- 4- Torque Sensors (\$675.00)
- 5- Li-Po Battery (\$62.99)

## Questions?